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Containing misinformation spreading in temporal social networks

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Many researchers from a variety of fields, including computer science, network science, and mathematics, have focused on how to contain the outbreaks of Internet misinformation that threaten social systems and undermine societal health. Most research on this topic treats the connections among individuals as static, but these connections change in time, and thus, social networks are also temporal networks. Currently, there is no theoretical approach to the problem of containing misinformation outbreaks in temporal networks. We thus propose misinformation spreading model for temporal networks and describe it using a new theoretical approach. We propose a heuristic-containing (HC) strategy based on optimizing final outbreak size that outperforms simplified strategies such as those that are random-containing (RC) and targeted-containing (TC). We verify the effectiveness of our HC strategy on both artificial and real-world networks by performing extensive numerical simulations and theoretical analyses. We find that the HC strategy dramatically increases the outbreak threshold and decreases the final outbreak threshold.

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Many communications platforms, e.g., Twitter, Facebook, email, WhatsApp, and mobile phones, allow numerous ways of sharing information [1–6]. One task for researchers is developing ways to distinguish between real news and the so-called "fake news" [7], which is essential in the process of intelligent decision-making [8–10]. For example, when the Severe Acute Respiratory Syndrome (SARS) spread across Guangzhou, China in 2003, the Chinese Southern Weekly published a newspaper article entitled "There is a Fatal Flu in Guangzhou." This information was forwarded over 126 million times by TV news and in other newspapers [11, 12], allowing the population to adopt simple but effective protective measures against being infected (e.g., staying at home, washing hands, or wearing masks). Misinformation, on the other hand, encourages irrational behavior and reckless decision-making. Its spreading can undermine societal well-being and sway the outcome of elections [13–16], including the 2016 US presidential election [17]. Scientists from different fields revealed that the network structures markedly alter the spreading phenomena. However, previous studies always assumed that the network structures do not change with time, and the effects of temporal characteristics of network structures are always neglected. In this paper, we take a step forward to study the misinformation spreading on temporal networks along with some possible containment strategies. Our results shed some light for decision-making for containing misinformation on social networks, and further containing public sentiment and maintain social stability.

I. INTRODUCTION

To contain the spreading of misinformation, we must understand the dynamic information spreading mechanisms that facilitate it [18–28]. Vosoughi *et al.*, [1] examined true and fake information on Twitter from 2006 to 2017 and found that misinformation spreads more quickly than true information. Using the spreading mechanisms common in real-data analysis, researchers have proposed several mathematical models to describe the spreading dynamics of true and fake information [29–34]. Moreno *et al.* [29] developed mean-field equations to describe the spread of classical misinformation on static scale-free networks that enable a theoretical study not requiring extensive numerical simulations. Borge-Holthoefer and Moreno [35] found that although there are no influential spreaders in the classical misinformation model presented in Ref. [29], nodes with high *k*-cores and ranking values are more likely to be the influential spreaders of true information and also of infectious diseases [36–40]. When we include the burst behavior of individuals in the misinformation model, hubs emerge as influential nodes [41]. Using real-world



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data, researchers found that social networks evolve with time, and thus evolving temporal networks more accurately represent the topology of real-world networks than static networks [42–45, 45–52].

Researchers have found that the temporal nature of networks strongly affects their spreading dynamics. Perra *et al.* [53] found that a temporal network behavior suppresses the spreading more effectively in susceptible-infected-susceptible (SIS) epidemic spreading than a static integrated network. Researchers have also found that the SIS and susceptible-infected-recovered (SIR) models on temporal networks exhibit the same outbreak threshold [54–56]. Nadini *et al.* [49] found that tightly connected clusters in temporal networks inhibit SIR processes, but accelerate SIS spreading. Pozzana *et al.* found that when a node attractiveness—its role as a preferential target for interactions—in temporal networks is heterogeneous, the contagion process is altered [57]. Karsai *et al.* [58] found that strong ties between individuals strongly inhibit the classical spreading dynamics of misinformation.

Several strategies for containing the spread of misinformation in temporal networks have been proposed [59–62]. Liu *et al.* [60] examined epidemic spreading on activity driven temporal networks and developed mean-field based theoretical approaches for three different control strategies, i.e., random, targeted, and egocentric. The egocentric strategy is the most effective. It immunizes a randomly selected neighbor of a node in the observation window. Other effective approaches using extensive numerical simulations have also been proposed [63–65]. For example, Holme and Liljeros [63] take into consideration the time variation of nodes and edges and propose a strategy for containing the outbreak of an epidemic based on the birth and the death of links.

Because there is still no theoretical approach to containing the spread of misinformation in temporal networks, we here systematically examine its spread in activity-driven networks. In this paper, we use an ignorant-spreader-refractory model to describe the spreading dynamics of misinformation on temporal networks. A generalized discrete Markovian approach is developed to describe the misinformation spreading dynamics, and well predicts the numerical results of the final outbreak size and threshold on both artificial and real-world temporal networks. We further propose an effective heuristic-containing strategy to contain the misinformation spreading, which performs much better than other contain strategies. The rest of the paper is organized as follows. Section II describes the misinformation spreading dynamics on temporal networks and develops a theory to describe the spreading dynamics. Section IV proposes three containment strategies. Section V describes the results of our extensive numerical stochastic simulations, which show that our suggested theory agrees with the numerical simulations. Section IV presents our conclusions.

II. MISINFORMATION SPREADING IN TEMPORAL NETWORKS

We here introduce our model for the spreading dynamics of misinformation in temporal networks.

A. Mathematical descriptions for temporal networks

The widely used approaches mathematically describing temporal networks tend to be either event-based or snapshot representations [47]. The event-based representation approach describes temporal networks using ordered events $\{u_i, v_i, t_i, \Delta t_i; i = 1, 2, \cdots\}$, where node u_i and v_i are connected at time t_i in the time period Δt_i . The snapshot approach describes temporal networks using a discrete sequence of static networks $\mathcal{G} = \{\mathcal{G}(1), \mathcal{G}(2), \cdots, \mathcal{G}(t_{\max})\}$, where $\mathcal{G}(t)$ is the snapshot network at time t, and t_{\max} is the number of snapshots of the temporal network. Each snapshot network $\mathcal{G}(t)$, contains N nodes, where N is fixed, and M_t edges. Thus the average temporal degree of snapshot network $\mathcal{G}(t)$ is $\langle k_t \rangle = 2M_t/N$. Using the adjacency matrix, the temporal network is $\mathcal{A} = \{\mathcal{A}(1), \mathcal{A}(2), \cdots, \mathcal{A}(t_{\max})\}$, where $\mathcal{A}(t)$ is the adjacency matrix of network $\mathcal{G}(t)$. To obtain a theoretical solution of the misinformation spreading dynamics on general temporal networks, we assume that the network is periodic boundary, i.e., $\mathcal{A}(t_{\max} + 1) = \mathcal{A}(1)$.

We here adopt the snapshot approach to describe temporal networks. As the meaning of the adjacency matrix in static networks, $\mathcal{A}_{uv}(t) = 1$ when nodes u and v are connected at time t, otherwise, $\mathcal{A}_{uv}(t) = 0$. Thus the degree $k_u(t)$ of node u at time t is $k_u(t) = \sum_{v=1}^{N} \mathcal{A}_{uv}(t)$ for undirected temporal networks. The average degree of node u in the temporal network \mathcal{G} is $\langle k_u(t) \rangle = \frac{1}{t_{\max}} \sum_{t=1}^{t_{\max}} k_u(t)$. Knowing the adjacency matrix \mathcal{A} we obtain the eigenvalues of \mathcal{A} . Here $\Lambda_1(\mathcal{A}) \Lambda_2(\mathcal{A}), \cdots$, and $\Lambda_N(\mathcal{A})$ are the eigenvalues of \mathcal{A} in decreasing order. The spectral radius is thus $\Lambda_1(\mathcal{A})$, which quantifies the threshold outbreak of epidemics in temporal networks.

B. Activity-driven networks

We use the classical activity-driven network [53] to model a temporal network with N nodes. We build the activity-driven network using the following steps.

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FIG. 1: Illustration of misinformation spreading on activity-driven networks with 20 nodes and temporal average degree is 5.

- 1. We assign to each node *i* an activity potential value x_i according to a given probability density distribution h(x). The activity of node *i* is $a_i = \eta x_i$, where η is a rescaling factor, i.e., at each time step node *i* is active with probability a_i . The higher the value of η , the higher the average degree of the temporal network. The higher the value of a_i , the higher the degree of node *i*. We assume that h(x) follows a power-law function, i.e., $h(x) \sim x^{-\gamma}$, where γ is the potential exponent. We make this assumption in order to generate a heterogeneous degree distribution temporal network. After further calculations we find $h(x) = \frac{\gamma-1}{\epsilon^{1-\gamma}}x^{-\gamma}$, $\langle k_t \rangle = 2m\langle a \rangle$, and $\langle a \rangle = \eta \langle x \rangle$, where $\langle x \rangle = \int_{\epsilon}^{\infty} xh(x)dx$, and ϵ is the minimum value of the activity potential x_i . Each active node has *m* edges, and each edge randomly links to a network node. An edge connects the same pair of nodes with probability m/N. Note that in the thermodynamic limit of a sparse temporal network, there are no multiple edges between nodes and non-local loops
- 2. At the end of time step t, we delete all edges in the network $\mathcal{G}(t)$.
- 3. We repeat steps 2 and 3 until t_{max} in order to generate temporal network \mathcal{G} .

C. Misinformation spreading model

We use an ignorant-spreader-refractory model to describe the spreading dynamics of misinformation [29]. Here nodes are classified as either ignorant, spreader, or refractory. Ignorant nodes are unaware that the information is false but are susceptible to adopting it. Spreader nodes are aware that the information is false and are willing to transmit them to ignorant nodes. Refractory nodes receive the misinformation but do not spread it. The misinformation spreading dynamics on temporal networks evolves as follows. We first randomly select a small fraction ρ_0 of spreader nodes to be seeded in network $\mathcal{G}(t_0)$, where $1 \le t_0 \le t_{\text{max}}$. We designate the remaining $1 - \rho_0$ nodes to be ignorant. At time step t each spreader i transmits the misinformation with probability λ to ignorant neighbors in the network $\mathcal{G}(t)$. Besides, each spreader i becomes a refractory node with a probability

$$\mu_i(t) = 1 - (1 - \mu)^{n(t)},\tag{1}$$

where μ is the intrinsic recovery probability, and n(t) is the number of nodes in the spreader and refractory states of node *i*. The dynamics evolve until there are no spreader nodes. Note that when *t* reaches t_{max} , the misinformation spreads on $\mathcal{G}(1)$ in the next time step. Figure 1 shows misinformation spreading on a temporal network.

III. THEORETICAL ANALYSIS

We here develop a generalized discrete Markovian approach to describe the misinformation spreading dynamics on temporal networks [54]. We denote $I_i(t) \in [0, 1]$, $S_i(t) \in [0, 1]$ and $R_i(t) \in [0, 1]$ to be the percentage of ignorant, spreader and refractory states respectively of node *i*, at time *t*. Because a node can only be in one of the three states, $I_i(t) + S_i(t) + R_i(t) = 1$.

An ignorant node *i* becomes a spreader with probability $p_i(t)$ at time *t*, where

$$p_{i}(t) = 1 - \prod_{j} [1 - \lambda \mathcal{A}_{ij}(t) S_{j}(t)].$$
(2)

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Here $\prod_{i} [1 - \lambda A_{ij}(t) S_j(t)]$ is the probability that node *i* has not received any misinformation from neighbors at time *t* in $\mathcal{G}(t)$.

$$I_i(t+1) = I_i(t) - I_i(t)p_i(t).$$
(3)

The decrease of $I_i(t)$ is equal to the increase of $S_i(t)$, because an ignorant node will become a spreader when it obtains the information from neighbors in state S. In addition, spreader *i* becomes refractory with a probability $\mu_i(t) = 1 - (1 - \mu) \sum_{j=1}^{N} A_{ij}(t) [S_j(t) + R_j(t)]$. Thus the evolution of node *i* in the spreader state is

$$S_i(t+1) = S_i(t) + I_i(t)p_i(t) - \mu_i(t)S_i(t).$$
(4)

The evolution of node i in the refractory state is

At time step t + 1, node *i* remains ignorant with a probability

$$R_i(t+1) = R_i(t) + \mu_i(t)S_i(t).$$
(5)

Using Eqs. (3)-(5), we obtain the fraction of nodes at time t in each state,

$$H(t) = \frac{1}{N} \sum_{i=1}^{N} H_i(t),$$
(6)

where $H \in \{I, S, R\}$. Note that in the steady state there are no spreader nodes, and only refractory and ignorant nodes exist. The fraction of nodes that receive the misinformation in the final state is $R(\infty) = R$. Here R is the order parameter of a continuous phase transition with λ . If the misinformation transmission probability λ is larger than the critical threshold, i.e., $\lambda > \lambda_c$, the size of the global misinformation is of the order of the system size. Otherwise, the global misinformation R = 0 for $\lambda \le \lambda_c$ is in the thermodynamic limit. At shorter times, a varnishing small fraction of nodes receive the misinformation, i.e., $S_i(t) \approx 0$ and $R_i(t) = 1 - S_i(t) - I_i(t) \approx 0$. The recovery probability in Eq. (1) of a spreader node i is $\mu_i(t) \approx \mu$, since node i must connect to a spreader that supplies the misinformation, and there is a low probability that it will connect to other spreader or refractory neighbors. Near the threshold point, the system has only a vanishingly small fraction of nodes in the spreader state, i.e., $S_i(t) \rightarrow 0$. Neglecting high order of $S_i(t)$ in Eq. (2), we have $p_i(t) = \sum_{j=1}^N \lambda A_{ij}(t) S_j(t)$. Submitting $p_i(t)$ into Eq. (4), we have

$$S_i(t+1) \approx \sum_{j=1}^{N} [(1-\mu) + \lambda \mathcal{A}_{ij}(t)\delta_{ij}]S_j(t), \tag{7}$$

where δ_{ij} is the Kronecker delta function, i.e., $\delta_{ij} = 1$ if i = j, and zero otherwise. We define the transmission tensor M to be

$$\mathbf{M}_{ij}^{tt'} = \delta^{t,t'+1}[(1-\mu)\delta_{ij} + \lambda \mathcal{A}_{ij}(t)].$$
(8)

We mask the tensorial origin of the space through the map $(i, t) \rightarrow \alpha = Nt + i$, where $1 \le \alpha \le N t_{\text{max}}$. Thus M can be interpreted as the weighted adjacency matrix of a cyclic graph, and be rewritten

$$\mathbf{M} = \begin{pmatrix} 0 & 1 - \mu + \lambda \mathcal{A}(1) & 0 & \cdots & 0 \\ 0 & 0 & 1 - \mu + \lambda \mathcal{A}(2) & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 1 - \mu + \lambda \mathcal{A}(t_{\max} - 1) \\ 1 - \mu + \lambda \mathcal{A}(t_{\max}) & 0 & 0 & \cdots & 0 \end{pmatrix}.$$
 (9)

Inserting Eq. (9) into (7), we have

$$\widehat{S}(\tau) = \mathbf{M}\widehat{S}(\tau - 1),\tag{10}$$

where $\widehat{S}(\tau)$ is the probability that a node is in the spreader state at each time step t during $[\tau t_{\max}, (\tau + 1)t_{\max}]$. Here $\widehat{S}(\tau)$ increases exponentially if the largest eigenvalue of M, denoted Λ_1 , is larger than 1. Thus the misinformation spreads, and the threshold condition is [54]

$$\Lambda_1(\mathbf{M}) = 1. \tag{11}$$

In an unweighted undirected network \mathcal{G} , the largest eigenvalue $\Lambda_1(\mathbf{M})$ of \mathbf{M} is

$$\Lambda_1(\mathbf{M}) = \Lambda_1(\mathbf{P}^{1/t_{\max}}),\tag{12}$$

where

$$\mathbf{P} = \sum_{t=1}^{t_{\text{max}}} (1 - \mu + \lambda \mathcal{A}(t)).$$
(13)

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IV. MISINFORMATION CONTAINING STRATEGIES

Because misinformation spreading on social networks can induce social instability, threaten political security, and endanger the economy, we propose three strategies—random, targeted, and heuristic—for containing the spread of misinformation in temporal networks using a given fraction of *containing* nodes f. We first immunize a fraction of f nodes using a static containment strategy. The misinformation then spreads on the residual temporal network. If node i is "immunized," it cannot be infected (transmit) by the misinformation received from neighbors (the misinformation to neighbors). Mathematically the immunized nodes equals the number of elements in \mathcal{V} , i.e., $|\mathcal{V}| = \lceil f \rceil$. We set $v_i = 1$ if node i is immunized, otherwise $v_i = 0$. After immunization, Eqs. (2)–(4) can be written

$$p_{i}(t) = 1 - \prod_{j} [1 - \lambda(1 - v_{j})\mathcal{A}_{ij}(t) I_{j}(t)], \qquad (14)$$

$$I_i(t+1) = I_i(t) - I_i(t)(1-v_i)p_i(t),$$
(15)

and

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$$S_i(t+1) = S_i(t) + I_i(t)(1-v_i)p_i(t) - \mu_i(t)S_i(t),$$
(16)

respectively. In an effective containing strategy the misinformation spreading dynamics is suppressed for a given fixed fraction f of immunized nodes, i.e., the objective function is

$$\min_{\mathcal{V}} \lim_{t \to \infty} \frac{1}{N} \sum_{i} R_i(t), \tag{17}$$

where the constraint conditions are Eqs. (15)–(16) and $V_i \in \{0,1\}$, $S_i(t) \in [0,1]$, $I_i(t) \in [0,1]$, and $R_i(t) \in [0,1]$. There are $\binom{fN}{N}$ possible solutions when containing a fraction of f nodes. Therefore, we can not obtain the optimal in polynomial time. As a result, finding an accurate solution for large-scale temporal networks and a finite immunization size f is difficult. To address this problem we propose three containment strategies.

- Strategy I: Random containment (RC). The most used strategy for containing the spread of misinformation is randomly immunizing a fraction of *f* nodes [66].
- Strategy II: Targeted containment (TC). Another intuitive way is to immunize the nodes with highest average degree $\langle k \rangle$ in the temporal network \mathcal{G} . Specifically, we first compute the average degree of each node i as $\langle k_i \rangle = \frac{1}{t_{\max}} \sum_{t=1}^{t_{\max}} \sum_{j=1}^{N} \mathcal{A}_{ij}(t)$. We then rank all nodes in descending order in the vector \mathcal{W} according to the average degree of each node. Finally we immunize the top $\lceil fN \rceil$ nodes of \mathcal{W} .
- Strategy III: Heuristic containment (HC). Using the TC, we apply an HC strategy. Because TC is much better than RC, we perform the HC strategy by replacing the immunization nodes. When the repeat time is very large, the immunized nodes reach an optimal value.
- (i) We initialize a vector W according to the descending order of the average degree of nodes. The first [fN] nodes of W are immunized, the final misinformation outbreak size is R_o, and W₀ denotes the first of [fN] nodes. The remaining nodes W₁ = W\W₀ are denoted a set.
- (ii) We randomly select nodes in W_0 and W_1 , denoted v_0 and v_1 , respectively. We switch their order in vector W and denote the new vector W_n . We immunize the first $\lceil fN \rceil$ nodes W_n and compute the final misinformation outbreak size R_n .
- (iii) When $R_n > R_o$, we update vector \mathcal{W} , i.e., $\mathcal{W} \to \mathcal{W}_n$. Otherwise, there is no change.
- (iv) We repeat steps (ii) and (iii) until $\frac{1}{t_s} \sum_{i=1}^{t_s} |\mathcal{W} \mathcal{W}_n| < \epsilon'$. In the simulations we set $t_s = 100$ and $\epsilon' = N^{-1}$.

V. NUMERICAL SIMULATIONS

For each numerical simulations, we first select a network $\mathcal{G}(t)$ and plant some initial seeds, then run the misinformation spreading dynamics until the system reaches a final state. The results averaged over 1500 times. Finally, we go through all possible network $\mathcal{G}(t)$ to plant the seeds. Therefore, the running time increases with t_{max} . For the activity-driven network, we set $N = 10^3$, $t_{\text{max}} = 20$, $\eta = 10$, m = 50, $\gamma = 2.1$, and $\epsilon = 10^{-3}$. Through extensive numerical simulations, we revealed

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FIG. 2: Misinformation spreading on activity-driven temporal networks. (a) The final misinformation outbreak size R, and the numerical variability χ versus the transmission probability λ with different values of recovery probability μ . In (a), the symbols are the numerical simulation results, and lines are the theoretical predictions by solving Eqs. (2)-(6).

that the phenomena presented in this paper are not qualitatively altered by the values of t_{max} . For real-world networks, we use the data collected by the Sociopatterns group [67], which records the interactions among the participants at a conference. The time resolution of the signal is 20 Sec. Because the temporal network is sparse, it is difficult for the information to spread in the original network. We thus aggregate the temporal network using four windows, w = 30min, 60min, 120min, and 240min. With the increase of w, the temporal network is more likely to be the same with the static aggregated network with $w = t_{\text{max}}$ of the Sociopatterns group data.

We use variability to locate the numerical network-sized dependent outbreak threshold [68, 69],

$$\chi = \frac{(\langle R^2 \rangle - \langle R \rangle^2)^{1/2}}{\langle R \rangle},\tag{18}$$

where R is the relative size of misinformation spreading at the steady state. At the outbreak threshold λ_c , χ exhibits a peak. When $\lambda \leq \lambda_c$, the global misinformation does not break out, but when $\lambda > \lambda_c$ the global misinformation does break out.

Figure 2 shows the misinformation spreading on activity-driven networks. Note that the final misinformation outbreak size R increases with λ . The larger the recovery probability μ , the lower the values of R because spreader nodes are less likely to transmit the misinformation to ignorant neighbors [see Fig. 2(a)]. Note that our theoretical and numerical predictions of the final misinformation outbreak size R agree. Figure 2(b) shows the variability χ is a function of λ . There is a peak at the misinformation outbreak threshold λ_c . Figure 3 shows λ_c versus μ in which λ_c increases linearly with μ . The theoretical predictions of λ_c obtained from Eq. (11) agree with the stochastic simulations.

Figure 4 shows misinformation spreading in real-world temporal networks. As in Fig. 2, R increases with λ and decreases with μ . As in SIR epidemic spreading [59], the effective outbreak threshold $(\lambda/\mu)_c$ is a constant value. Besides, when the value aggregating window w is small, there are fewer opportunities for spreaders to transmit the misinformation to ignorant neighbors. Thus the misinformation does not break out globally, i.e., there are smaller values of R for smaller w. In other words, the time-varying character of temporal network slows down the misinformation spreading. Once again, our theoretical results agree with the numerical simulations.

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FIG. 3: The outbreak threshold λ_c versus μ . The symbols represent the stochastic simulation threshold, and line is the theoretical prediction by solving Eq. (11).

We next examine the performances of our proposed strategies for mitigating misinformation spreading on artificial and realworld temporal networks. Figure 5 shows R versus λ for different values of the fraction of containing nodes f. Note that Rdecreases with f because no more nodes receive the misinformation. Note also that the TC strategy performs much better than the RC strategy because the higher degree nodes $\langle k \rangle$ are contained, and spreaders can no longer transmit the misinformation to ignorant. Thus when we immunize the same fraction of containing nodes, the values of R for the TC strategy are smaller than those for the RC strategy. For example, when f = 0.5, using the RC strategy about 30% of the nodes are informed by the misinformation, but using the TC strategy, none are informed by the misinformation. Besides, the outbreak threshold λ_c decreases with f. Figures 5(c)–5(d) show the numerical predictions for λ_c . Since the misinformation can not outbreak when f = 0.5, there is no peak for χ in Fig. 5(d).

Figure 6 shows that the HC strategy performs better than the TC strategy. We set $\lambda = 0.2$ and 0.3 in 6(a) and 6(b), respectively, and compare the final misinformation spreading size R with f. We find that the misinformation spreading dynamics are suppressed when we use the HC strategy. For example, when f = 0.05 and $\lambda = 0.3$, few nodes are informed by the misinformation, i.e., $R \approx 0.01$ when we use the HC strategy, but when we use the TC strategy to contain the misinformation the fraction of nodes informed by the misinformation is finite, i.e., $R \approx 0.25$. Our theoretical results agree with the numerical simulation results.

An effective containing strategy with a fraction of immunized node f and a small outbreak threshold λ_c greatly decreases the final misinformation outbreak size R. Figure 7 shows the effective outbreak threshold $(\lambda/\mu)_c$ versus f on activity-driven networks for the RC, TC, and HC strategies. Here $(\lambda/\mu)_c$ increases with f, and $(\lambda/\mu)_c$ is the largest using the HC strategy when f is fixed. When f is sufficiently large, no λ value can induce a global misinformation outbreak. We denote f_c the critical probability that at least a fraction of f_c nodes must be containing to halt misinformation spreading in temporal networks. We find that the values of f_c for the HC containing strategy are the smallest of all containing strategies. The f_c value for the RC strategy is 5 times the f_c value for the TC strategy and the f_c value for the TC strategy is 2.5 times the f_c value for the HC strategy. Thus the HC strategy is the most effective.

We finally examine real-world networks to verify the effectiveness of our proposed three strategies. Figure 8 compares the performances of the TC and HC strategies by examining R versus f for given values of λ . As in Fig. 6, the HC strategy most effectively contains the misinformation spreading on temporal networks irrespective of the values of λ . Besides, Fig. 9 shows

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FIG. 4: Misinformation spreading on real-world temporal networks. The final misinformation outbreak size R versus λ on ACM Hypertex conference data set with aggregating window (a) w = 30 min, (b) w = 60 min, (c) w = 120 min and (d) w = 240 min. The symbols are the numerical simulation results, and lines are the theoretical predictions by solving Eqs. (2)-(6).

that the effective outbreak threshold $(\lambda/\mu)_c$ is the smallest when using the HC strategy. Thus our theory accurately predicts the numerical simulation results.

VI. CONCLUSIONS

We have systematically examined the dynamics of misinformation spreading on temporal networks. We use activity driven networks to describe temporal networks, and use a discrete Markovian chain to describe the spreading dynamics. We find that the global misinformation outbreak threshold correlates with the topology of temporal networks. Using extensive numerical simulations, we find that our theoretical predictions agree with numerical predictions in both artificial and real-world networks.

To contain misinformation spreading on temporal networks, we propose three strategies, random containing (RC), targeted containing (TC), and heuristic containing (HC) strategies. We perform numerical simulations and theoretical analysis on both artificial and four real-world networks and find that the HC strategy outperforms the other two strategies maximize the outbreak









FIG. 5: Containing misinformation spreading dynamics on activity-driven temporal networks. The final misinformation outbreak size R (a) and variability χ (c) versus the transmission probability λ under the RC strategy. R (b) and χ (d) versus λ under the TC strategy. In (a) and (b), the lines are the theoretical predictions by solving Eqs. (14)-(16) and (6), and symbols are the numerical simulation results.

threshold and minimize the final outbreak size. Our proposed containing strategy expands our understanding of how to contain public sentiment and maintain social stability. For instance, before the spreading of a piece of misinformation, we can implement our suggested strategies on the temporal networks to contain the outbreak size of the misinformation.

Our suggested generalized discrete Markovian approach can accurately describe the time-varying character of temporal social networks by using the temporal adjacency matrix $\mathcal{A}(t)$. As a result, the final misinformation outbreak size and outbreak threshold can be well predicted by our theory. Our developed HC strategy can well suppress the misinformation spreading on both artificial and real-world networks by using the knowledge of theoretical outbreak size R. In future studies, our suggested theory needs

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FIG. 6: Effectiveness of TC and HC strategies on activity-driven networks. The final misinformation outbreak size R versus f for a given values of $\lambda = 0.2$ (a) and $\lambda = 0.3$ (b). The lines and symbols are the theoretical and the numerical predictions of R, respectively. The theoretical predictions are obtained by solving Eqs. (14)-(16) and (6). Numerical simulation is time-consuming when perform containing strategies, therefore we only show several numerical results with large steps.

further improvement to extend its applications. On the one hand, compared with the TC and HC strategies, the better performance of HC strategy comes with a heavy-cost, i.e., a prior knowledge of the system network structure (the adjacency matrix at each time t) and dynamics (knowledge of the parameters μ and λ to predict the outbreak size R). The RC strategy does not need any information of the network, and TC only requires knowledge of the adjacency matrix at each time t. On the other hand, it is time-consuming with the increase of t_{max} and N, therefore we should reduce the dimension of the system in future researches. Finally, we should develop a method to estimate dynamical parameters when using the HC strategy in real situations.

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FIG. 7: The effective outbreak threshold $(\lambda/\mu)_c$ versus the fraction of containing nodes f on activity-driven networks for RC strategy (a), TC strategy (b), HC strategy (c), and the comparison of the three strategies (d). The lines and symbols are the theoretical and numerical predictions of $(\lambda/\mu)_c$, respectively. The vertical line represents the critical probability of f_c . The theoretical predictions are obtained by solving by solving Eqs. (14)-(16) and (11).

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FIG. 8: Effectiveness of TC and HC strategies on ACM Hypertex conference data set. R versus f with aggregating window (a) w = 30 min, (c) w = 60 min, (e) w = 120 min and (g) w = 240 min for $\lambda = 0.2$. R versus f with (b) w = 30 min, (d) w = 60 min, (f) w = 120 min and (h) w = 240 min for $\lambda = 0.3$. The lines and symbols are the theoretical and numerical predictions of R, respectively. The theoretical predictions are obtained by solving Eqs. (14)-(16) and (6).

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FIG. 9: Comparing the effectiveness of RC, TC and HC strategies on ACM Hypertex conference data set with aggregating window (a) w = 30 min, (b) w = 60 min, (c) w = 120 min and (d) w = 240 min. The theoretical predictions are obtained by solving by solving Eqs. (14)-(16) and (11). The symbols are numerical simulation results.

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